

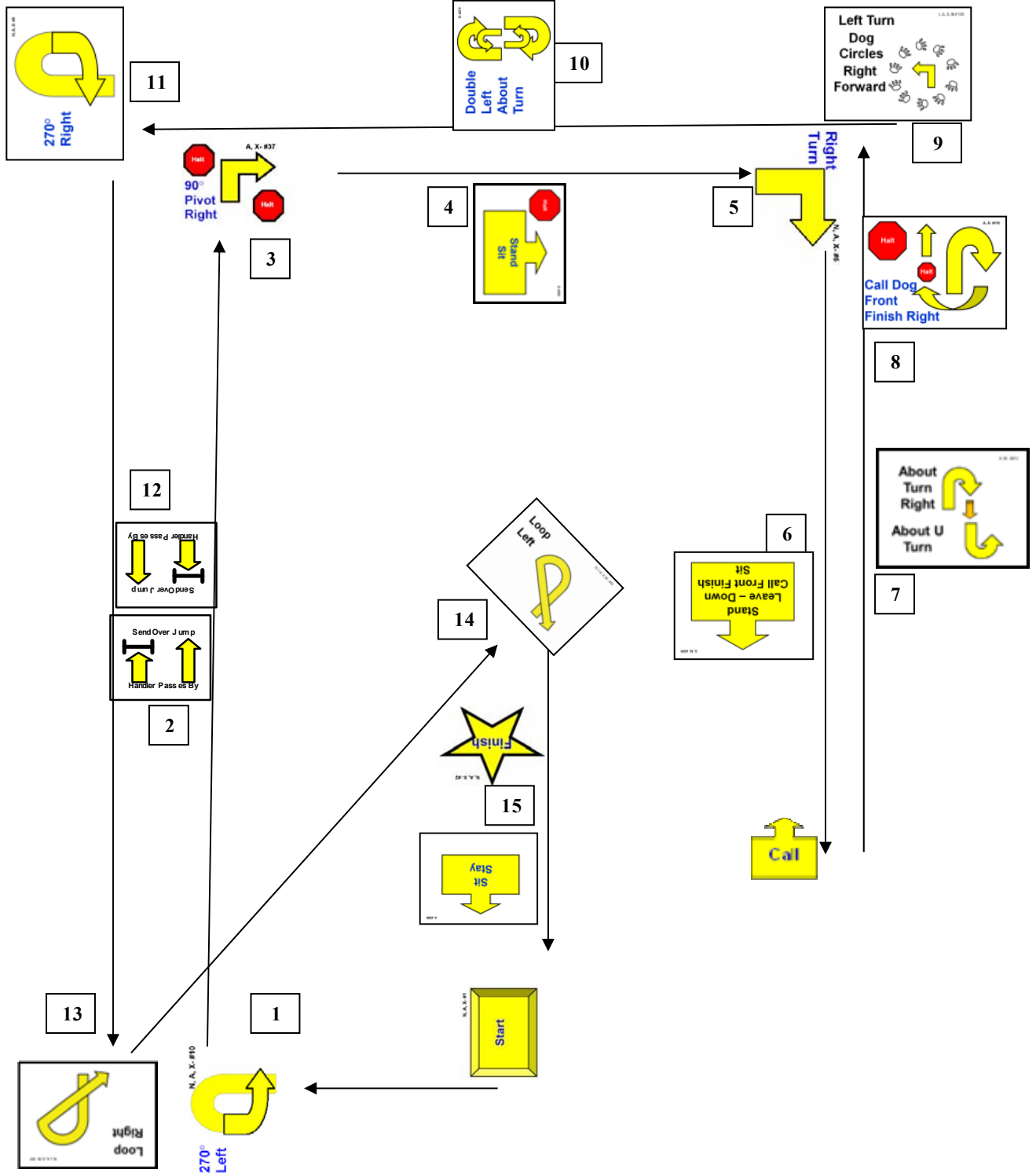
Start

1. Stand – Right Turn – Forward (214s)
2. Halt–Recall Over Jump–Finish–About Turn Fwd (303s)/ Arrow (303A)
3. HALT – 90° Pvt Rt - HALT (106s)
4. Moving Stand – Walk Around (203s)

5. Right Turn (5)
6. Halt–Leave–Recall–Finish Left–Sit (318s)
7. Dog Spin Left–Fwd (313)
8. Dog Spin Right–Fwd (312)
9. Left Turn – Dog Circles Right (120)

10. Double Left About Turn (211)
11. Halt–Send Away Sit–Return–Follow Arrow Right (307s) / Arrow (307A)
12. Serpentine Weave Once (24)
13. Halt – Pivot Left – Fwd (117s)

14. Slow Pace (17)
 15. Normal Pace (19)
- FINISH**



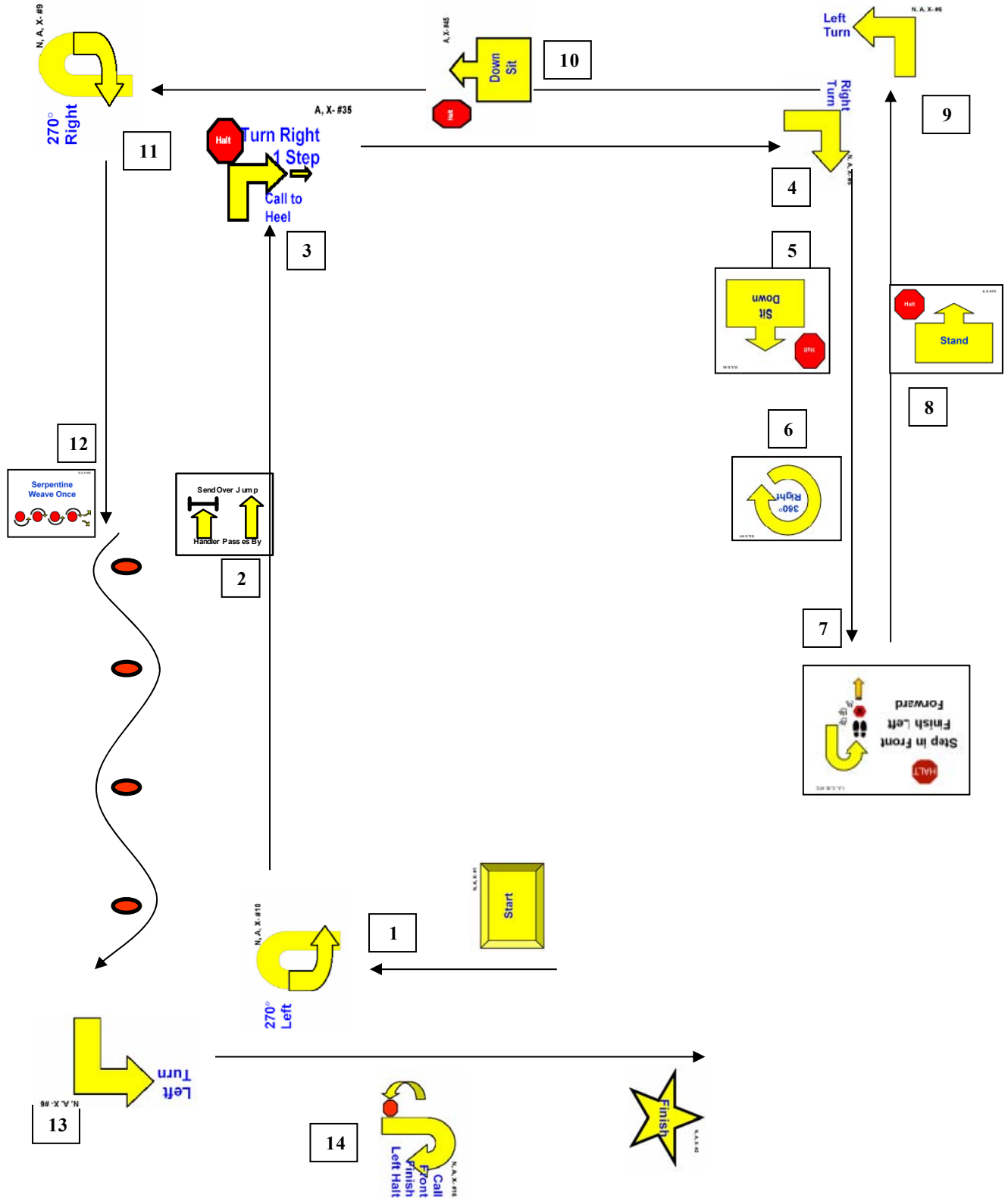
Start

- 1. 270 Left Turn (10)
- 2. Send Over Jump (103)
- 3. HALT – 90 Pvt Rt - HALT (106s)
- 4. Halt – Stand - Sit (202s)
- 5. Right Turn (5)

- 6. Stand-Leave - Down - Call Front- Finish - Sit (209s)
- 7. About Turn Right – About U Turn (212)
- 8. Halt – Call Front – Finish Right (110s)

- 9. Left Turn – Dog Circles Right (120)
- 10. Double Left About (211)
- 11. 270 Right Turn (9)
- 12. Send Over Jump(103)

- 13. Loop Right (37)
- 14. Loop Left (38)
- FINISH**
- 15. SIT STAY (298)



Start

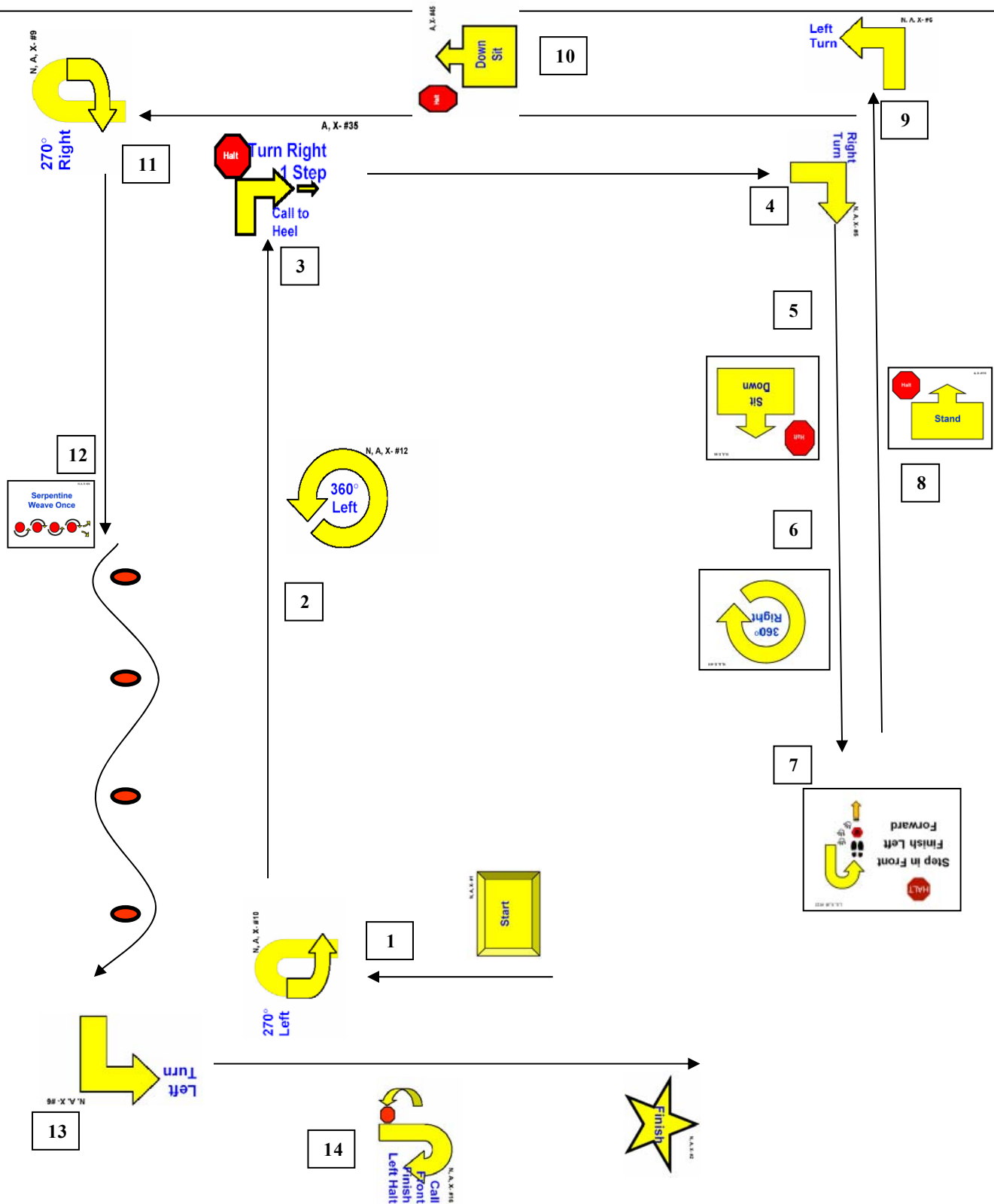
- 1. 270° Left Turn (10)
- 2. Send Over Jump (103)
- 3. HALT – Rt 1 Step-
Call to Heel,
HALT (104s)
- 4. Right Turn (5)
- 5. Halt – Sit - Down (4s)

- 6. 360° Right Turn (11)
- 7. Halt–Step In Front–
Finish Left–Fwd
(122s)
- 8. Halt – Stand (115s)

- 9. Left Turn (6)
- 10. HALT–Down-Sit
(114s)
- 11. 270° Right Turn (9)
- 12. Serpentine Weave
Once (24)
- 13. Left Turn (6)

- 14. Call Front - Finish
Left – HALT (16s)

Finish



Start

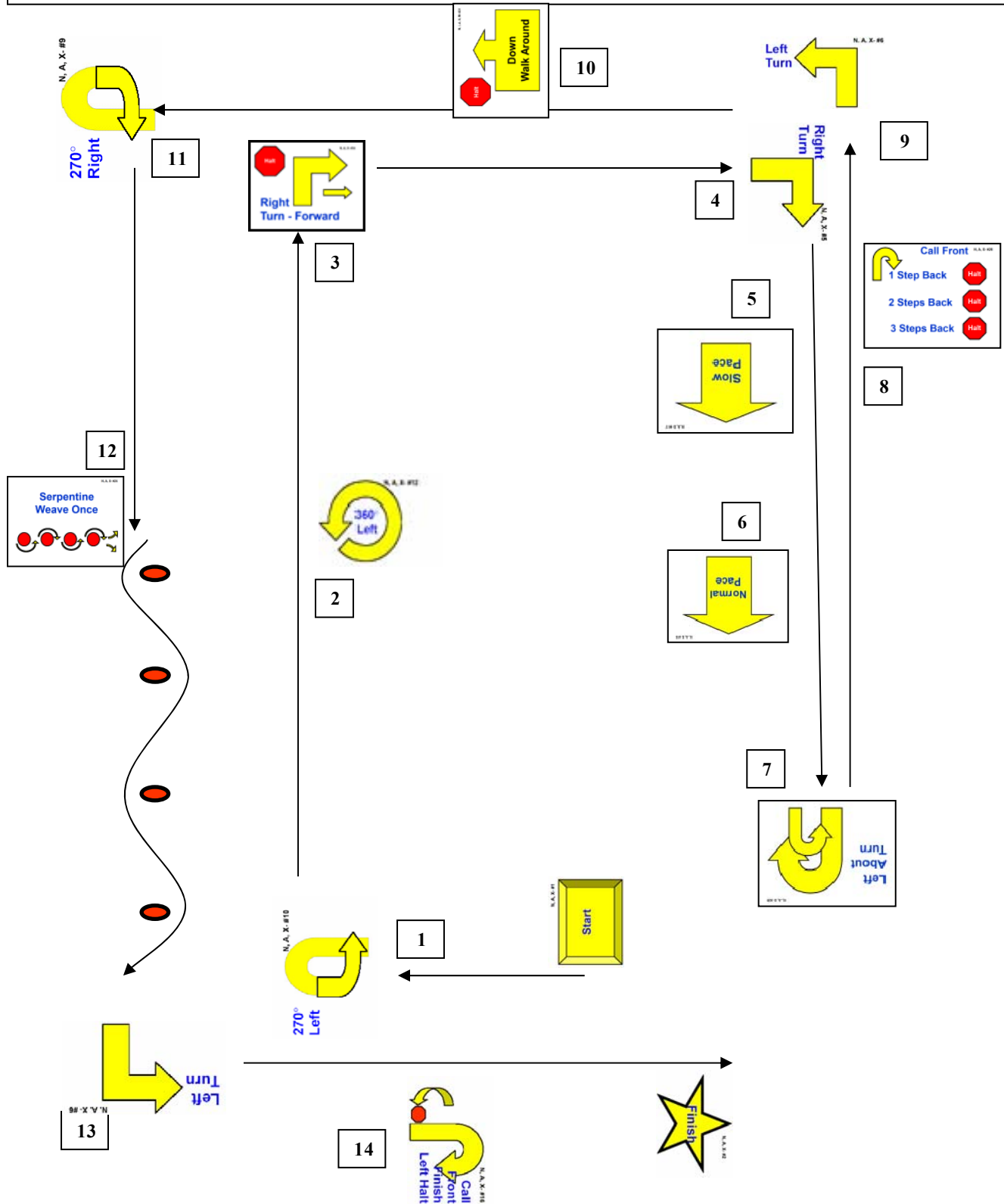
- 1. 270° Left Turn (10)
- 2. 360° Left Turn (12)
- 3. HALT – Rt 1 Step-
Call to Heel,
HALT (104s)
- 4. Right Turn (5)

- 5. Halt – Sit - Down (4s)
- 6. 360° Right Turn (11)
- 7. Halt–Step In Front–
Finish Left–Fwd
(122s)
- 8. Halt – Stand (115s)

- 9. Left Turn (6)
- 10. HALT–Down–Sit
(114s)
- 11. 270° Right Turn (9)
- 12. Serpentine Weave
Once (24)

- 13. Left Turn (6)
- 14. Call Front - Finish
Left – HALT (16s)

Finish



Start

- 1. 270 Left Turn (10)
- 2. 360 Left Turn (12)
- 3. Halt-Right Turn-Fwd (33s)
- 4. Right Turn (5)
- 5. Slow Pace (17)

- 6. Normal Pace (19)
- 7. Left About Turn (29)
- 8. Call Front-1,2,3 Steps Backward- Fwd 26s)
- 9. Left Turn (6)

- 10. HALT – Down – Walk Around Dog (31s)
- 11. 270 Right Turn (9)
- 12. Serpentine Weave Once (24)

- 13. Left Turn (6)
- 14. Call Front - Finish Left – HALT (16s)

Finish